# Signaling with cpNode 

Seth Neumann seth@modelrailroadcontrolsystems.com<br>Chuck Catania - chuck@modelrailroadcontrolsystems.com

http://www.modelrailroadcontrolsystems.com/

## Assumptions:

- This clinic is focused on implementing a signaling system using cpNodes, CMRInet and JMRI
- You know what you want to model
- You are generally familiar with principles of Railroad Signaling
- You know something about JMRI or CATS and will be using a computer to control signaling on your railroad
- Hard CTC machines can be done easily with cpNode but we recommend going to the considerable effort and expense of a hard panel only after the design is proven on a "glass" panel


## Agenda

- Control Point Layout
- Establishing blocks \& detection
- Fascia switches/control panels
- Switch motor control
- CMRI configuration in JMRI
- CMRInet Configuration and Topology
- Configuration examples and worksheets


## Control Point layout-1



Whole Siding ( $30 \mathrm{i} / \mathrm{o}$ )

- Inputs: (8)
- 6 Detection Blocks
- 2 Fascia switches
- Outputs: (22)
- 2 double high signals (@ $5=10$ )
$\cdot 2$ high signals (@3=6)
- 2 low signals = (@2=4)
- 2 switch motor lines ( $@ 1=2$ )

Control Point ( $15 \mathrm{i} / \mathrm{o}$ )

- Inputs: (4)
- 3 Detection Blocks
- 1 Fascia switch
- Outputs: (11)
- 1 double high signal (@5)
-1 high signal (@3)
-1 low signal = (@2)
- 1 switch motor line (@1)



## Control Point layout-2

- Siding with industry switches
- Switching signal - no change in hardware
- Possible locks? - add an input or do locally



## Control Point layout - 3

- cpNode per control point
- Each cpNode has 16 i/o lines and can be expanded to a total of 144 in groups 16 or 32 (IOX 16/32)
- A standard control point requires 15 lines, or a single cpNode.
- cpNode per Siding
- A simple siding requires 30 lines and can be implemented with a cpNode and a single IOXı6
- cpNode per Interlocking
- More complicated control points - such as interlockings may be achieved by adding more i/o to the node. At 144 lines of $\mathrm{i} / \mathrm{o}$, a fully expanded cpNode can handle almost any interlocking used on a model railroad


## Disclaimer: Chuck and Seth's secret

## plan for morlo domínatínn:

- We want to offer the cpNode with a standard sketch that does ABS/APB with local switch control when no "code line" is present
- All "vital logic" is on the node (just like the prototype)
- When CMRInet "Code Line" is active the vital logic will accept commands from the CTC machine and execute them IF and ONLY IF the vital logic concludes it is safe to do so.
- John Plocher has done some work on a subset of the ATCS commands used by real CTC machines on real Code Lines.
- This is an additional reason for using the node per control point approach


## Powering Signals -1

- We assume you are using modern 3-LED signals that will operate from the local 5 volt supply. A modern LED will light acceptably at $5-10 \mathrm{~mA}$ current, so a whole siding with 20 heads, assuming all LEDs came on at startup, will draw 200 mA .
- 200mA for LEDs can be supplied by the onboard regulator of the BB-Leo (Arduino) on the cpNode. If you need more current, consider an external 5 V supply and be sure to tie the ground side back to the cpNode ground. We like 3 LED common anode signals (such as those from BLMA) but common cathode and two LED signals may be used.

| Color | Resistor to give $\mathbf{1 0 m A}$ @ $\mathbf{5 V}$ | Watts |
| :--- | :--- | :--- |
| Green | 270 ohm | $1 / 8$ or greater |
| Yellow | 220 ohm | $1 / 8$ or greater |
| Red | 330 ohm | $1 / 8$ or greater |
| Lunar | 6,000 ohm | $1 / 8$ or greater |

- These values yield a pleasing balance of colors, but YMMV as $20 \%$ of males have some degree of diminished color vision. Pads for limiting resistors are provided on cpNode and IOX16/32.


## Powering Signals -2

If you need to drive loads with higher voltage or if you need to exceed 25 mA per line or a total of more than 160 mA per device, use our CSNK, which can sink up to 500 mA at 60 V . The CSNK must be connected to an IOX16 and all supply grounds must tied together. CSNK ensures compatibility with older 12 systems and high current devices such as incandescent lamps.


Distance - the LEDs are driven by DC levels, so the limiting factor is resistance of the wire. We use 24 ga $\mathrm{CAT}_{5}$ cable (each one supports 2 heads) with a resistance of $\sim 275$ ohms per loop mile. Typical limiting resistor values at 5 V are 220-330 Ohms, so keeping the wire at $10 \%$ of the resistance yields a limit of about 6ooft: unlikely to be an issue on a model railroad

## Blocks

- Each block (main, siding, OS, some auxiliary track such as staging) must be detected. Blocks are typically 1.25-2.0 train lengths except for OS sections and interlockings
- Current Detectors
- Best overall performance
- More expensive: \$6-\$18 per block
- Require resistor wheel sets on each car for best performance
- Optical Detectors
- Good for point detection - some prefer them for OS sections
- Less expensive: \$3-\$20 per detector but may need more than one
- May be sensitive to ambient light and require some fiddling to get calibrated
- Good for stopping blocks, impingement detectors


## Detector types

- Current sensing -
- DCCOD (Chubb/JLC/SLIQ) \$17 per
- RR-Cirkits BOD-8 \$ 6.25 in 8s
- cpOD (future MRCS offer in Alpha Testing now)
- Others - we like the transformer type
- Optical -
- Paisley - \$3 in 8s
- IRDOT - From Heathcote (UK) \$17 per
- Boulder Creek Nightscope \$20 per
- Asian Cheapies - \$1- \$3 per


## Current Detector Plans-1

Two approaches but you can mix and match:
Centralized -

- we co-located a cpNode and IOX32 with power distribution for a client. He has a power distribution panel on each wall of a $50^{\prime} x$ 15 ' room. Each wall has about 48 blocks. ( 48 i/o and 48 detectors)
- Favors larger motherboards such as Chubb's ODMB with DCCOD or cpOD(M) or RRCirkits BOD-8
- Longer 12 Ga runs from panel to the blocks. Runs should be limited to about 50'


South Wall Power Panel at Ted Stephens' OL\&K: Open tomorrow AM

## Current Detector Plans -2

## Distributed

- Distributed detectors with the control point. For control points with 3 blocks we like cpOD(M) on an ODX4 motherboard, for a siding per node model either two ODX4s or a BOD-8 (a couple of detector segments won't be used) will work well. You can use individual detectors wired into the feeders (cpOD)
- An advantage is that our forthcoming SafeTrak feature will allow the node to perform basic ABS functionality without a host computer if the detectors are connected locally


Node 90 at Walt Schedler's Shasta Division - under
Dunsmuir

## Detectors: to Motherboard or....

Some current detectors plug into motherboards, others have you install the coils on the feeder

- Motherboards:
- Let you do the power wiring once and you can swap detectors in and out for trouble shooting
- Motherboards can be centralized for easier adjustment and to see local occupancy lights
- Add cost and connections (points of failure)
- Chubb style motherboards (for DCCOD and cpOD(M)) come in 12 (ODMB) and 4 position (ODX4)
- Detector outputs are logic levels and don't change quickly so you can use the 6oo' limit above although shorter is better. If remoting the "tombstone" transformers try to keep them to $25^{\prime}$ from the main detector
We like motherboards!


## Switch Machines - 1



## Switch Machines - 2

|  | Stall Motor | Servo | Twin Coil |
| :--- | :--- | :--- | :--- |
| Market Position | Most common | Challenger | Less popular but <br> still used: Kato, <br> Atlas |
| Power | 12V @ 20mA, <br> constant | 5V @ 15omA while <br> moving | 12V @ .5A pulse, <br> must turn off |
| Controller | SMC12, RSMC, <br> SMD-8 | Tam Valley, Arduino <br> (Sketches on | SCSD-8, SM1, SM2 |
| Arduino) |  |  |  |

## Switch Controls 3 - Stall Motor

- Stall Motor:
- SMC-12

- RSMC
- Free standing
- Stuff option for one RSMC on cpNode



## Switch Controls 4 - Servo

- TAM Valley
- Various Arduini Sketches including Charlie Bedard, use any handy Arduino
- Write your own Sketch that combines node and servo timing and use cpNode hardware
- Physical:
- TAM Valley servo mount
- Brunel servo mount
- Others out there

- Servos do not have internal contacts to switch frog polarity so you'll need an external relay (TV) or a micro switch mounted on the bracket (Brunel) or a frog juicer if you want to switch frog polarity (recommended)
- Servos draw about 150 mA while moving, so for most applications you'll want an external 5 V supply (ground side tied to logic ground)


## Fascia/Panel Controls

Use any type of switch you like - I like Rick Fortin's slide switch recessed behind the fascia - doesn't snag or break off. Keeps the fascia clean.


- Switch can be wired directly to cpNode input but requires that computer be on.
- Local panel to provide local control when no computer, Dennis Drury designed a switch panel using an RSMC that looks for a 5 V line from the computer power supply, 5 V isn't present, the switch panel is in local control. We should be offering this as a "community" product shortly
- "Safetrack" local sketch in absence of CMRI "Code Line"
- Usually one input line per Control Point, but a second line can be used for a switch lock. The lock can also be wired in series with the switch so the switch can't get to the input unless the lock is unlocked (with Dispatcher permission)


## CMRInet Configuration

- Old-School: configure as a SUSIC with 24 line DIN and DOUT boards. If you only need 16 inputs, configure a DIN and just use 17-24. This approach also works if you want to use QBASIC or VBASIC
- Use standard JMRI or QBASIC or VBASIC configuration tools


## CMRInet - C/MRI Communication Protocol

- Designed by Bruce Chubb in 1985 to be a simple, easy to implement, serial data messaging system.
- Robust, industrial grade network technology for moving data between a host (master) and node (slave) in a connected network.
- CMRInet specification submitted to the NMRA Layout Control Specification (LCS) Repository as LCS-9.10.
- NMRA - CMRI Special Interest Group (SIG) established 2015.

C/MRI 30! Celebrating the $30^{\text {th }}$ anniversary of C/MRI at NMRA Portland.

## CMRInet Topology

- Bruce Chubb assumed the network started at the host computer and worked linearly out to the furthest node, his RS232/485 converter includes a terminator at the computer and the user would terminate at the far end.
- RS485 does not allow branches (not to say that modelers don't cheat $\langle\mathrm{g}>$ ), so best practice is to have a single CMRInet snaking around your layout with no taps or branches
- Install a terminator at the far end.
- More modern practice is to use an RS-485 USB dongle at the computer, use a terminator at the computer as well as the far end. This is standard RS-485. The Computer does not have to be at one end, but if not, ensure that ends (only) are terminated.
- We recommend CAT5 or better data cable rather than shielded 2 pair as the performance is comparable, the price is lower and you don't need to worry about shielding (which is best left to experts)


## CMRInet Connection



The serial communication connection to all C/MRI network nodes is through a four-wire cable. One pair of wires is for transmission, the other pair for receive. The network is defined as half-duplex, RS-422/485, Master/Slave.

The connection from the control computer (Host) to the C/MRI network is through an interface device which converts USB or RS-232 signals to RS-422/RS-485.

Nodes in a C/MRI network are connected daisy chain fashion, node to node.

## CMRInet Timing

- Most Classic CMRI installations have a few large nodes and run at 9600 bps. Each node requires about 30 mS to respond so a 10 node system had a poll cycle time of about 300 mS (or 3 polls per second). This is plenty fast for our purposes.
- We recommend running faster, 28,8oo or greater, to keep the poll cycle in the 300 mS range with a larger number of nodes. The bus will run as fast as 115 K .
- There is no problem with mixing and matching cpNode and classic nodes as long as they are set to the same speed - the classic nodes can also work at 115 K

Proposed JMRI Updates to Support cpNodes


## Proposed JMRI Updates to Support cpNodes



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## Proposed JMRI Updates to Support cpNodes



## Use My Layout as an Example

- Main line ~ 10o'
- Switches
- 12 mainline switches (dispatcher controlled)
- 6 controlled switches connecting to sidings
- 6 industry spurs connect to the main
- Signals - All high signals are BLMA US\&S H2 Searchlights
- 14 (but 3 not visible so they have repeaters only) double head
- 14 (but 3 not visible so they have repeaters only) single head high
- 10 (but 2 not visible so it they have repeaters only) Low
- 10 dwarf (some used in place of low signals in yards, industry areas)
- 3 Sidings, 1 Wye, crossover in the middle of the loop
- Blocks (35):
- 12 OS (main line switches)
- 3 main with sidings
- 3 sidings, 1 main in cross over, 3 Wye sections, 4 staging
- 10 Main line


## My Track Plan



## Layout example

- UP (ex-WP) used western 3 block route signaling, note the real WP did not "bond" the sidings so the most favorable indication into the siding was approach
- 3 sidings + staging
- 2 of the sidings are connected to industry tracks or a yard
- No intermediate signals (uncommon in the prototype but very common in the model world)


## Example - control point per node



## Bitl of Materials:

 cpNode per Control Point|  |  |  | Inputs |  | Outputs |  | total i/o | cpNode | $10 \times 16$ | cpOD(M) | ODX4 | RSMC | Dongle |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Node |  | Milepost | fascia | Blocks | Switch | Signal Lines |  |  |  |  |  |  |  |
|  | Staging + Wye | F044 | 7 | 10 |  | $7 \quad 40$ | 64 | 1 | 3 | 10 | 3 | ${ }^{6}$ |  |
| 11 | E Hearst | F039 | 1 | 3 | 1 | 10 | 15 | 1 | 0 | 3 | 1 | 0 |  |
| 12 | W Hearst | F038 | 1 | 3 | 1 | 10 | 15 | 1 | 0 | 3 | 1 | 0 |  |
| 13 | Niles JCT | F030 | 1 | 3 | 1 | 11 | 16 | 1 | 0 | 3 | 1 | 0 |  |
| 14 | E NUMMI | M004 | 1 | 2 | 1 | 10 | 14 | 1 | 0 | 2 | 1 | 0 |  |
| 15 | W NUMMI | M005 | 1 | 2 | 1 | 10 | 14 | 1 | 0 | 2 | 1 | 0 |  |
| 16 | Yard Lead | M009 | 1 | 3 | 1 | 8 | 13 | 1 | 0 | 3 | 1 | 0 |  |
| 17 | E Milpitas | M010 | 2 | 2 | 2 | 11 | 17 | 1 | 1 | 2 | 1 | 1 |  |
| 18 | W Milpitas | M012 | 1 | 3 | 1 | 9 | 14 | 1 | 0 | 3 | 1 | 0 |  |
| 19 | Diridon | M019 | 1 | 3 | 1 | 8 | 13 | 1 | 0 | 3 | 1 | 0 |  |
| 20 | Niles Back | NIO10 | 1 | 2 | 1 | 12 | 16 | 1 | 0 | 2 | 1 | 0 |  |
|  | Computer |  |  |  |  |  |  |  |  |  |  |  | 1 |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | needed |  |  |  |  |  |  | 11 | 4 | 36 | 13 | 7 | 1 |
|  | 10\% Sparing |  |  |  |  |  |  | 2 | 1 | 4 | 1 | 1 | 1 |
|  | total order |  |  |  |  |  | 211 | 13 | 5 | 40 | 14 | 8 | 2 |

## Examples - Full siding work sheet



## Bitl of Material: cpNode per Siding

|  |  |  |  | Inputs |  | Outputs |  | total i/o | cpNode | IOX16 | cpOD(M) | ODX4 | RSMC | Dongle |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Node |  | Milepost |  | fascia | Blocks | Switch | Signal Lines |  |  |  |  |  |  |  |
| 10 | Staging + Wye | F044 | F043 | 7 | 10 | 7 | 40 | 64 | 1 | 3 | 10 | 3 | 6 |  |
| 11 | Hearst | F039 | F038 | 2 | 6 | 2 | 20 | 30 | 1 | 1 | 6 | 2 | 1 |  |
| 12 | Niles Cutoff | F030 | N1010 | 2 | 5 | 2 | 23 | 32 | 1 | 1 | 5 | 2 | 1 |  |
| 13 | E NUMMI | M004 | M005 | 3 | 7 | 3 | 28 | 41 | 1 | 2 | 7 | 2 | 2 |  |
| 14 | E Milpitas | M010 |  | 3 | 5 | 3 | 20 | 31 | 1 | 1 | 5 | 2 | 2 |  |
| 15 | Diridon | M019 |  | 1 | 3 | 1 | 8 | 13 | 1 | 0 | 3 | 1 | 0 |  |
|  | Computer |  |  |  |  |  |  |  |  |  |  |  |  | 1 |
|  | needed |  |  |  |  |  |  |  | 6 | 8 | 36 | 12 | 12 | 1 |
|  | 10\% Sparing |  |  |  |  |  |  |  | 1 | 1 | 4 | 1 | 2 | 1 |
|  | total order |  |  |  |  |  |  |  | 7 | 9 | 40 | 13 | 14 | 2 |

## Example - "Opportunistic Clusters"



## Bill of Materials:

Opportunistic Clusters

|  |  |  |  |  | puts | Outputs |  | total i/o | cpNode | 10x16 | cpod(M) | ODX4 | RSMC | Dongle |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Node |  | Milepost |  | $\begin{aligned} & \mathrm{fasc} \\ & \text { ia } \\ & \hline \end{aligned}$ | Blocks | Switch | Signal Lines |  |  |  |  |  |  |  |
| 10 | Staging + Wye | F044 | F043 | 7 | 10 | 7 | 40 | 64 | 1 | 3 | 310 | 3 | 6 |  |
| 11 | Hearst | F039 | NIO10 | 4 | 11 | 4 | 20 | 62 | 1 | 3 | 11 | 3 | 3 |  |
| 13 | E NUMMI | M004 | M005 | 6 | 12 | 6 | 48 | 72 | 1 | 4 | 412 | 3 | 5 |  |
| 13 | Diridon | M019 |  | 1 | 3 | 1 | 8 | 13 | 1 | 0 | 3 | 1 | 0 |  |
|  | Computer |  |  |  |  |  |  |  |  |  |  |  |  | 1 |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | needed |  |  |  |  |  |  |  | 4 | 10 | 36 | 10 | 14 | 1 |
|  | 10\% Sparing |  |  |  |  |  |  |  | 1 | 1 | 4 | 1 | 2 | 1 |
|  | total order |  |  |  |  |  |  | 211 | 5 | 11 | 40 | 11 | 16 | 2 |

## Example - SMINI Replacement

 Come see it!

## Bill of Materials: <br> SMINI Replacement

|  |  |  |  | Inputs |  | Outputs |  | total i/o | cpNode | IOX16 | cpOD(M) | ODX4 | RSMC | Dongle |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Node |  | Milepost |  | fascia | Blocks | Switch | Signal Lines |  |  |  |  |  |  |  |
|  | Radum Side | FO44 | NIO10 | 11 | 21 | 11 | 84 | 126 | 1 | 7 | 21 | 6 | 10 |  |
|  | Milpitas Side | M004 | M005 | 7 | 15 | 7 | 56 | 85 | 1 | 5 | 15 | 4 | 6 |  |
|  | Computer |  |  |  |  |  |  |  |  |  |  |  |  | 1 |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | needed |  |  |  |  |  |  |  | 2 | 12 | 36 | 10 | 16 | 1 |
|  | 10\% Sparing |  |  |  |  |  |  |  | 1 | 2 | 4 | 1 | 2 | 1 |
|  | total order |  |  |  |  |  |  | 211 | 3 | 14 | 40 | 11 | 18 | 2 |

## Appendix - the cpNode family


cpNode

IOX16



RSMC


ODX4


IOX32


CSNK


MOLEX

Visit us at www.modelrailroadcontrolsystems.com

## References:

- Our (MRCS) website http://www.modelrailroadcontrolsystems.com/
- Bruce Chubb's excellent manuals at
http://www.jlcenterprises.net/Products.htm\#Manual
- Texas Instruments RS485 Application Note
http://www.google.com/url?sa=t\&rct=j\&q=\&esrc=s\&source=web\&cd=2\&cad=ri a\&uact=8\&ved=oCCcQFjAB\&url=http\%3A\%2F\%2Fwww.ti.com\%2Flit\%2Fan\%2 Fslla272b\%2Fslla272b.pdf\&ei=UCFQVcCgIMWzoQTF8oHQDQ\&usg=AFQjCN GfNyOdKHcıuZHfxBvNlognOeiCog\&sig2=PlID2oJIA4kyFDeeIJ-leA\&bvm=bv
- Other Vendors - see our resource section:
http://www.modelrailroadcontrolsystems.com/information/

